Econ 204 2019

Lecture 11

Outline

1. Derivatives
2. Chain Rule
3. Mean Value Theorem
4. Taylor's Theorem

Derivatives

Definition 1. *Let* $f : I \to \mathbf{R}$*, where* $I \subseteq \mathbf{R}$ *is an open interval.* f *is* differentiable *at* $x \in I$ *if*

$$\lim_{h \to 0} \frac{f(x+h) - f(x)}{h} = a$$

for some $a \in \mathbf{R}$*.*

This is equivalent to $\exists a \in \mathbf{R}$ such that

$$\lim_{h \to 0} \frac{f(x+h) - (f(x) + ah)}{h} = 0$$

$$\Leftrightarrow \quad \forall \varepsilon > 0 \ \exists \delta > 0 \text{ s.t. } 0 < |h| < \delta \Rightarrow \left| \frac{f(x+h) - (f(x) + ah)}{h} \right| < \varepsilon$$

$$\Leftrightarrow \quad \forall \varepsilon > 0 \ \exists \delta > 0 \text{ s.t. } 0 < |h| < \delta \Rightarrow \frac{|f(x+h) - (f(x) + ah)|}{|h|} < \varepsilon$$

$$\Leftrightarrow \quad \lim_{h \to 0} \frac{|f(x+h) - (f(x) + ah)|}{|h|} = 0$$

Derivatives

Definition 2. *If* $X \subseteq \mathbf{R}^n$ *is open,* $f : X \to \mathbf{R}^m$ *is* differentiable at $x \in X$ *if* $\exists T_x \in L(\mathbf{R}^n, \mathbf{R}^m)$ *such that*

$$\lim_{h \to 0, h \in \mathbf{R}^n} \frac{|f(x+h) - (f(x) + T_x(h))|}{|h|} = 0 \tag{1}$$

f *is* differentiable *if it is differentiable at all* $x \in X$.

Note that T_x is uniquely determined by Equation (1).

The definition requires that **one** linear operator T_x works no matter how h approaches zero.

In this case, $f(x) + T_x(h)$ is the best linear approximation to $f(x+h)$ for sufficiently small h.

Big-Oh and little-oh

Notation:

- $y = O(|h|^n)$ as $h \to 0$ – read "y is big-Oh of $|h|^n$" – means

$$\exists K, \delta > 0 \text{ s.t. } |h| < \delta \Rightarrow |y| \leq K|h|^n$$

- $y = o(|h|^n)$ as $h \to 0$ – read "y is little-oh of $|h|^n$" – means

$$\lim_{h \to 0} \frac{|y|}{|h|^n} = 0$$

Note that $y = O(|h|^{n+1})$ as $h \to 0$ implies $y = o(|h|^n)$ as $h \to 0$.

Using this notation: f is differentiable at $x \Leftrightarrow \exists T_x \in L(\mathbf{R}^n, \mathbf{R}^m)$ such that

$$f(x+h) = f(x) + T_x(h) + o(h) \text{ as } h \to 0$$

More Notation

Notation:

- df_x is the linear transformation T_x
- $Df(x)$ is the matrix of df_x with respect to the standard basis.

  This is called the *Jacobian* or *Jacobian matrix* of f at x
- $E_f(h) = f(x+h) - (f(x) + df_x(h))$ is the *error term*

Using this notation,

$$f \text{ is differentiable at } x \Leftrightarrow E_f(h) = o(h) \text{ as } h \to 0$$

What's $Df(x)$?

Now compute $Df(x) = (a_{ij})$. Let $\{e_1, \ldots, e_n\}$ be the standard basis of $\mathbf{R}^n$. Look in direction e_j (note that $|\gamma e_j| = |\gamma|$).

$$
\begin{aligned}
o(\gamma) &= f(x+\gamma e_j) - \Big(f(x) + T_x(\gamma e_j) \Big) \\
&= f(x+\gamma e_j) - \left(f(x) + \begin{pmatrix} a_{11} & \cdots & a_{1j} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mj} & \cdots & a_{mn} \end{pmatrix} \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \gamma \\ 0 \\ \vdots \\ 0 \end{pmatrix} \right) \\
&= f(x+\gamma e_j) - \left(f(x) + \begin{pmatrix} \gamma a_{1j} \\ \vdots \\ \gamma a_{mj} \end{pmatrix} \right)
\end{aligned}
$$

For $i = 1, \ldots, m$, let f^i denote the i^{th} component of the function f:

$$\begin{aligned} f^i(x + \gamma e_j) - \left(f^i(x) + \gamma a_{ij}\right) &= o(\gamma) \\ \text{so } a_{ij} &= \frac{\partial f^i}{\partial x_j}(x) \end{aligned}$$

Derivatives and Partial Derivatives

Theorem 1 (Thm. 3.3)**.** *Suppose* $X \subseteq \mathbf{R}^n$ *is open and* $f : X \to \mathbf{R}^m$ *is differentiable at* $x \in X$. *Then* $\frac{\partial f^i}{\partial x_j}(x)$ *exists for* $1 \leq i \leq m$, $1 \leq j \leq n$, *and*

$$Df(x) = \begin{pmatrix} \frac{\partial f^1}{\partial x_1}(x) & \cdots & \frac{\partial f^1}{\partial x_n}(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial f^m}{\partial x_1}(x) & \cdots & \frac{\partial f^m}{\partial x_n}(x) \end{pmatrix}$$

i.e. the Jacobian at x *is the matrix of partial derivatives at* x .

Derivatives and Partial Derivatives

Remark: If f is differentiable at x, then all first-order partial derivatives $\frac{\partial f^i}{\partial x_j}$ exist at x. However, the converse is false: existence of all the first-order partial derivatives does not imply that f is differentiable.

The missing piece is continuity of the partial derivatives:

Theorem 2 (Thm. 3.4)**.** *If all the first-order partial derivatives $\frac{\partial f^i}{\partial x_j}$ ($1 \leq i \leq m$, $1 \leq j \leq n$) exist and are continuous at x, then f is differentiable at x.*

Directional Derivatives

Suppose $X \subseteq \mathbf{R}^n$ open, $f : X \to \mathbf{R}^m$ is differentiable at x, and $|u| = 1$.

$$\begin{aligned} & f(x+\gamma u) - (f(x) + T_x(\gamma u)) = o(\gamma) \text{ as } \gamma \to 0 \\ \Rightarrow \quad & f(x+\gamma u) - (f(x) + \gamma T_x(u)) = o(\gamma) \text{ as } \gamma \to 0 \\ \Rightarrow \quad & \lim_{\gamma \to 0} \frac{f(x+\gamma u) - f(x)}{\gamma} = T_x(u) = Df(x)u \end{aligned}$$

i.e. the directional derivative in the direction u (with $|u| = 1$) is

$$Df(x)u \in \mathbf{R}^m$$

Chain Rule

Theorem 3 (Thm. 3.5, Chain Rule)**.** *Let $X \subseteq \mathbf{R}^n$, $Y \subseteq \mathbf{R}^m$ be open, $f : X \to Y$, $g : Y \to \mathbf{R}^p$. Let $x_0 \in X$ and $F = g \circ f$. If f is differentiable at x_0 and g is differentiable at $f(x_0)$, then $F = g \circ f$ is differentiable at x_0 and*

$$\begin{aligned} dF_{x_0} &= dg_{f(x_0)} \circ df_{x_0} \\ &\quad \textit{(composition of linear transformations)} \\ DF(x_0) &= Dg(f(x_0))Df(x_0) \\ &\quad \textit{(matrix multiplication)} \end{aligned}$$

Remark: The statement is exactly the same as in the univariate case, except we replace the univariate derivative by a linear transformation. The proof is more or less the same, with a bit of linear algebra added.

Mean Value Theorem

Theorem 4 (Thm. 1.7, Mean Value Theorem, Univariate Case)**.** *Let* $a, b \in \mathbf{R}$. *Suppose* $f : [a, b] \to \mathbf{R}$ *is continuous on* $[a, b]$ *and differentiable on* (a, b). *Then there exists* $c \in (a, b)$ *such that*

$$\frac{f(b) - f(a)}{b - a} = f'(c)$$

that is, such that

$$f(b) - f(a) = f'(c)(b - a)$$

Proof. Consider the function

$$g(x) = f(x) - f(a) - \frac{f(b) - f(a)}{b - a}(x - a)$$

Then $g(a) = 0 = g(b)$. Note that for $x \in (a, b)$,

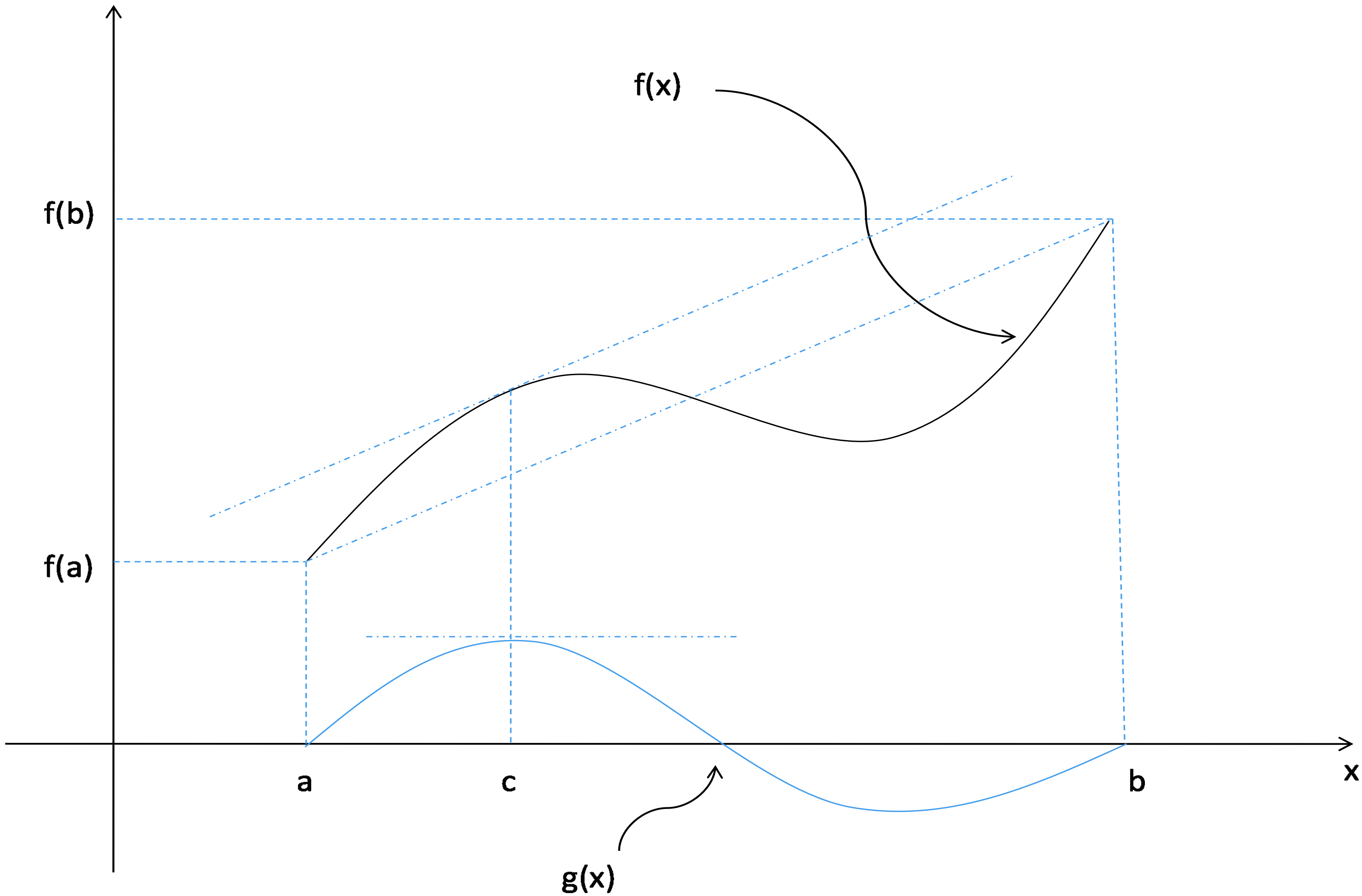
$$g'(x) = f'(x) - \frac{f(b) - f(a)}{b - a}$$

so it suffices to find $c \in (a, b)$ such that $g'(c) = 0$.

Case I: If $g(x) = 0$ for all $x \in [a, b]$, choose an arbitrary $c \in (a, b)$, and note that $g'(c) = 0$, so we are done.

Case II: Suppose $g(x) > 0$ for some $x \in [a, b]$. Since g is continuous on $[a, b]$, it attains its maximum at some point $c \in (a, b)$. Since g is differentiable at c and c is an interior point of the domain of g, we have $g'(c) = 0$, and we are done.

Case III: If $g(x) < 0$ for some $x \in [a, b]$, the argument is similar to that in Case II. □


f(x)
f(b)
f(a)
a
c
b
x
g(x)

Mean Value Theorem

Notation:

$$\ell(x, y) = \{\alpha x + (1 - \alpha)y : \alpha \in [0, 1]\}$$

is the line segment from x to y.

Theorem 5 (Mean Value Theorem). *Suppose* $f : \mathbf{R}^n \to \mathbf{R}$ *is differentiable on an open set* $X \subseteq \mathbf{R}^n$*,* $x, y \in X$ *and* $\ell(x, y) \subseteq X$*. Then there exists* $z \in \ell(x, y)$ *such that*

$$f(y) - f(x) = Df(z)(y - x)$$

Notice that the statement is exactly the same as in the univariate case. For $f : \mathbf{R}^n \to \mathbf{R}^m$, we can apply the Mean Value Theorem to each component, to obtain $z_1, \ldots, z_m \in \ell(x, y)$ such that

$$f^i(y) - f^i(x) = Df^i(z_i)(y - x)$$

However, we cannot find a single z which works for every component.

Note that each $z_i \in \ell(x, y) \subset \mathbf{R}^n$; there are m of them, one for each component in the range.

Mean Value Theorem

Theorem 6. *Suppose* $X \subset \mathbf{R}^n$ *is open and* $f : X \to \mathbf{R}^m$ *is differentiable. If* $x, y \in X$ *and* $\ell(x, y) \subseteq X$*, then there exists* $z \in \ell(x, y)$ *such that*

$$
\begin{aligned}
|f(y) - f(x)| &\leq |df_z(y - x)| \\
&\leq \|df_z\| |y - x|
\end{aligned}
$$

Mean Value Theorem

Remark: To understand why we don't get equality, consider $f : [0,1] \to \mathbf{R}^2$ defined by

$$f(t) = (\cos 2\pi t, \sin 2\pi t)$$

f maps $[0,1]$ to the unit circle in $\mathbf{R}^2$. Note that $f(0) = f(1) = (1,0)$, so $|f(1) - f(0)| = 0$. However, for any $z \in [0,1]$,

$$\begin{aligned} |df_z(1-0)| &= |2\pi(-\sin 2\pi z, \cos 2\pi z)| \\ &= 2\pi\sqrt{\sin^2 2\pi z + \cos^2 2\pi z} \\ &= 2\pi \end{aligned}$$

Taylor's Theorem – $\mathbf{R}$

Theorem 7 (Thm. 1.9, Taylor's Theorem in $\mathbf{R}$)**.** *Let $f : I \to \mathbf{R}$ be n-times differentiable, where $I \subseteq \mathbf{R}$ is an open interval. If $x, x+h \in I$, then*

$$f(x+h) = f(x) + \sum_{k=1}^{n-1} \frac{f^{(k)}(x)h^k}{k!} + E_n$$

where $f^{(k)}$ is the k^{th} derivative of f and

$$E_n = \frac{f^{(n)}(x+\lambda h)h^n}{n!} \text{ for some } \lambda \in (0,1)$$

Motivation: Let

$$
\begin{aligned}
T_n(h) &= f(x) + \sum_{k=1}^{n} \frac{f^{(k)}(x)h^k}{k!} \\
&= f(x) + f'(x)h + \frac{f''(x)h^2}{2} + \cdots + \frac{f^{(n)}(x)h^n}{n!} \\
T_n(0) &= f(x) \\
T_n'(h) &= f'(x) + f''(x)h + \cdots + \frac{f^{(n)}(x)h^{n-1}}{(n-1)!} \\
T_n'(0) &= f'(x) \\
T_n''(h) &= f''(x) + \cdots + \frac{f^{(n)}(x)h^{n-2}}{(n-2)!} \\
T_n''(0) &= f''(x) \\
&\vdots \\
T_n^{(n)}(0) &= f^{(n)}(x)
\end{aligned}
$$

so $T_n(h)$ is the unique n^{th} degree polynomial such that

$$\begin{aligned} T_n(0) &= f(x) \\ T_n'(0) &= f'(x) \\ &\vdots \\ T_n^{(n)}(0) &= f^{(n)}(x) \end{aligned}$$

Taylor's Theorem – $\mathbf{R}$

Theorem 8 (Alternate Taylor's Theorem in $\mathbf{R}$). *Let $f : I \to \mathbf{R}$ be n times differentiable, where $I \subseteq \mathbf{R}$ is an open interval and $x \in I$. Then*

$$f(x+h) = f(x) + \sum_{k=1}^{n} \frac{f^{(k)}(x)h^k}{k!} + o\left(h^n\right) \text{ as } h \to 0$$

If f is $(n+1)$ times continuously differentiable, then

$$f(x+h) = f(x) + \sum_{k=1}^{n} \frac{f^{(k)}(x)h^k}{k!} + O\left(h^{n+1}\right) \text{ as } h \to 0$$

Remark: The first equation in the statement of the theorem is essentially a restatement of the definition of the n^{th} derivative. The second statement is proven from Theorem 1.9, and the continuity of the derivative.

C^k Functions

Definition 3. *Let $X \subseteq \mathbf{R}^n$ be open. A function $f : X \to \mathbf{R}^m$ is* continuously differentiable *on X if*

- *f is differentiable on X and*

- *df_x is a continuous function of x from X to $L(\mathbf{R}^n, \mathbf{R}^m)$, with respect to the operator norm $\|df_x\|$*

f is C^k if all partial derivatives of order $\leq k$ exist and are continuous in X.

C^k Functions

Theorem 9 (Thm. 4.3)**.** *Suppose* $X \subseteq \mathbf{R}^n$ *is open and* $f : X \to \mathbf{R}^m$*. Then* f *is continuously differentiable on* X *if and only if* f *is* C^1*.*

Taylor's Theorem – Linear Terms

Theorem 10. *Suppose* $X \subseteq \mathbf{R}^n$ *is open and* $x \in X$*. If* $f : X \to \mathbf{R}^m$ *is differentiable, then*

$$f(x+h) = f(x) + Df(x)h + o(h) \text{ as } h \to 0$$

This is essentially a restatement of the definition of differentiability.

Taylor's Theorem – Linear Terms

Theorem 11 (Corollary of 4.4)**.** *Suppose* $X \subseteq \mathbf{R}^n$ *is open and* $x \in X$*. If* $f : X \to \mathbf{R}^m$ *is* C^2*, then*

$$f(x+h) = f(x) + Df(x)h + O\left(|h|^2\right) \text{ as } h \to 0$$

Taylor's Theorem – Quadratic Terms

We treat each component of the function separately, so consider $f : X \to \mathbf{R}$, $X \subseteq \mathbf{R}^n$ an open set. Let

$$D^2 f(x) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2}(x) & \frac{\partial^2 f}{\partial x_2 \partial x_1}(x) & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_1}(x) \\ \frac{\partial^2 f}{\partial x_1 \partial x_2}(x) & \frac{\partial^2 f}{\partial x_2^2}(x) & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_2}(x) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_1 \partial x_n}(x) & \cdots & \cdots & \frac{\partial^2 f}{\partial x_n^2}(x) \end{pmatrix}$$

$$\begin{aligned} f \in C^2 \;&\Rightarrow\; \frac{\partial^2 f}{\partial x_i \partial x_j}(x) = \frac{\partial^2 f}{\partial x_j \partial x_i}(x) \\ &\Rightarrow\; D^2 f(x) \text{ is symmetric} \\ &\Rightarrow\; D^2 f(x) \text{ has eigenvectors that are an orthonormal basis} \\ &\qquad \text{and thus can be diagonalized} \end{aligned}$$

Taylor's Theorem – Quadratic Terms

Theorem 12 (Stronger Version of Thm. 4.4)**.** *Let* $X \subseteq \mathbf{R}^n$ *be open,* $f : X \to \mathbf{R}$*,* $f \in C^2(X)$*, and* $x \in X$*. Then*

$$f(x+h) = f(x) + Df(x)h + \frac{1}{2}h^\top(D^2 f(x))h + o\left(|h|^2\right) \text{ as } h \to 0$$

If $f \in C^3$*,*

$$f(x+h) = f(x) + Df(x)h + \frac{1}{2}h^\top(D^2 f(x))h + O\left(|h|^3\right) \text{ as } h \to 0$$

Characterizing Critical Points

Definition 4. *We say f has a* saddle *at x if $Df(x) = 0$ but f has neither a local maximum nor a local minimum at x.*

Characterizing Critical Points

Corollary 1. *Suppose $X \subseteq \mathbf{R}^n$ is open and $x \in X$. If $f : X \to \mathbf{R}$ is C^2, there is an orthonormal basis $\{v_1, \ldots, v_n\}$ and corresponding eigenvalues $\lambda_1, \ldots, \lambda_n \in \mathbf{R}$ of $D^2 f(x)$ such that*

$$\begin{aligned} f(x+h) &= f(x + \gamma_1 v_1 + \cdots + \gamma_n v_n) \\ &= f(x) + \sum_{i=1}^{n} \left(Df(x) v_i\right) \gamma_i + \frac{1}{2} \sum_{i=1}^{n} \lambda_i \gamma_i^2 + o\left(|\gamma|^2\right) \end{aligned}$$

where $\gamma_i = h \cdot v_i$.

1. *If $f \in C^3$, we may strengthen $o\left(|\gamma|^2\right)$ to $O\left(|\gamma|^3\right)$.*

2. *If f has a local maximum or local minimum at x, then*

$$Df(x) = 0$$

3. *If* $Df(x) = 0$, *then*

- $\lambda_1, \ldots, \lambda_n > 0 \Rightarrow f$ *has a local minimum at* x
- $\lambda_1, \ldots, \lambda_n < 0 \Rightarrow f$ *has a local maximum at* x
- $\lambda_i < 0$ *for some* i, $\lambda_j > 0$ *for some* $j \Rightarrow f$ *has a saddle at* x
- $\lambda_1, \ldots, \lambda_n \geq 0$, $\lambda_i > 0$ *for some* $i \Rightarrow f$ *has a local minimum or a saddle at* x
- $\lambda_1, \ldots, \lambda_n \leq 0$, $\lambda_i < 0$ *for some* $i \Rightarrow f$ *has a local maximum or a saddle at* x
- $\lambda_1 = \cdots = \lambda_n = 0$ *gives no information.*

Proof. (Sketch) From our study of quadratic forms, we know the behavior of the quadratic terms is determined by the signs of the eigenvalues. If $\lambda_i = 0$ for some i, then we know that the quadratic form arising from the second partial derivatives is identically zero in the direction v_i, and the higher derivatives will determine the behavior of the function f in the direction v_i. For example, if $f(x) = x^3$, then $f'(0) = 0$, $f''(0) = 0$, but we know that f has a saddle at $x = 0$; however, if $f(x) = x^4$, then again $f'(0) = 0$ and $f''(0) = 0$ but f has a local (and global) minimum at $x = 0$. $\square$