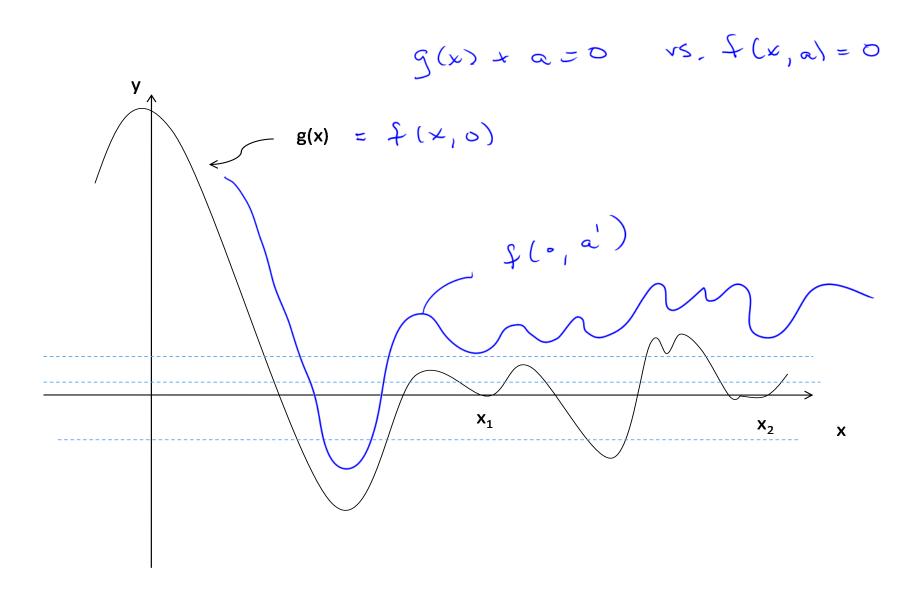
### Econ 204 2021

#### Lecture 13

#### Outline

### O. Transversality theorem

- 1. Fixed Points for Functions
- 2. Brouwer's Fixed Point Theorem
- 3. Fixed Points for Correspondences
- 4. Kakutani's Fixed Point Theorem
- 5. Separating Hyperplane Theorems



### Transversality

Suppose  $f: \mathbf{R}^n \times \mathbf{R}^p \to \mathbf{R}^m$ . We care about the parameterized family of equations

$$f(x,a) = 0$$

where, as above, we interpret  $a \in \mathbb{R}^p$  to be a vector of parameters that indexes the function  $f(\cdot, a)$ .

For a given a, we are interested in the set of solutions

$$\{x \in X : f(x,a) = 0\}$$

and the way that this correspondence depends on a.

If f is separable in a, that is, f(x,a) = g(x) + a, then we can use Sard's Theorem (PS6 2010).

### Transversality Theorem

Separability is strong, and not required: If f depends on a in a nonseparable fashion, it is enough that from any solution f(x,a)=0, any directional change in f can be achieved by arbitrarily small changes in x and a.

**Theorem 4** (Thm. 2.5', Transversality Theorem). Let  $X \subseteq \mathbb{R}^n$  and  $A \subseteq \mathbb{R}^p$  be open, and  $f: X \times A \to \mathbb{R}^m$  be  $C^r$  with  $r \ge 1 + \max\{0, n-m\}$ . Suppose that 0 is a regular value of f. Then there is a set  $A_0 \subseteq A$  such that  $A \setminus A_0$  has Lebesgue measure zero and for all  $a \in A_0$ , 0 is a regular value of  $f_a = f(\cdot, a)$ .

**Remark:** Notice the important difference between the statement that 0 is a regular value of f (one of the assumptions of the Transversality Theorem), and the statement that 0 is a regular value of  $f_a$  for a fixed  $a \in A_0$  (part of the conclusion of the Transversality Theorem). 0 is a regular value of f if and only if Df(x,a) has full rank for every (x,a) such that f(x,a)=0. Instead, for fixed  $a_0 \in A_0$ , 0 is a regular value of  $f_{a_0}=f(\cdot,a_0)$  if and only if  $D_x f(x,a_0)$  has full rank for every x such that  $f_{a_0}(x)=f(x,a_0)=0$ .

**Remark:** Consider the important special case in which n=m, so we have as many equations (m) as endogenous variables (n). In this case, suppose f is  $C^1$  (note that  $1=1+\max\{0,n-n\}$ ). If 0 is a regular value of f, that is, Df(x,a) has rank n=m for every (x,a) such that f(x,a)=0, then by the Transversality Theorem there is a set  $A_0\subset A$  such that  $A\setminus A_0$  has Lebesgue measure zero and for every  $a_0\in A_0$ ,  $D_xf(x,a_0)$  has rank n=m for all x such that  $f(x,a_0)=0$ .

Fix  $a_0 \in A_0$  and  $x_0$  such that  $f(x_0, a_0) = 0$ . By the Implicit Function Theorem, there exist open sets  $A^*$  containing  $a_0$  and  $X^*$  containing  $x_0$ , and a  $C^1$  function  $x: A^* \to X^*$  such that

• 
$$x(a_0) = x_0$$

• f(x(a), a) = 0 for every  $a \in A^*$ 

• if  $(x,a) \in X^* \times A^*$  then

$$f(x,a) = 0 \iff x = x(a)$$

that is,  $x_0$  is locally unique, and x(a) is locally unique for each  $a \in A^*$ 

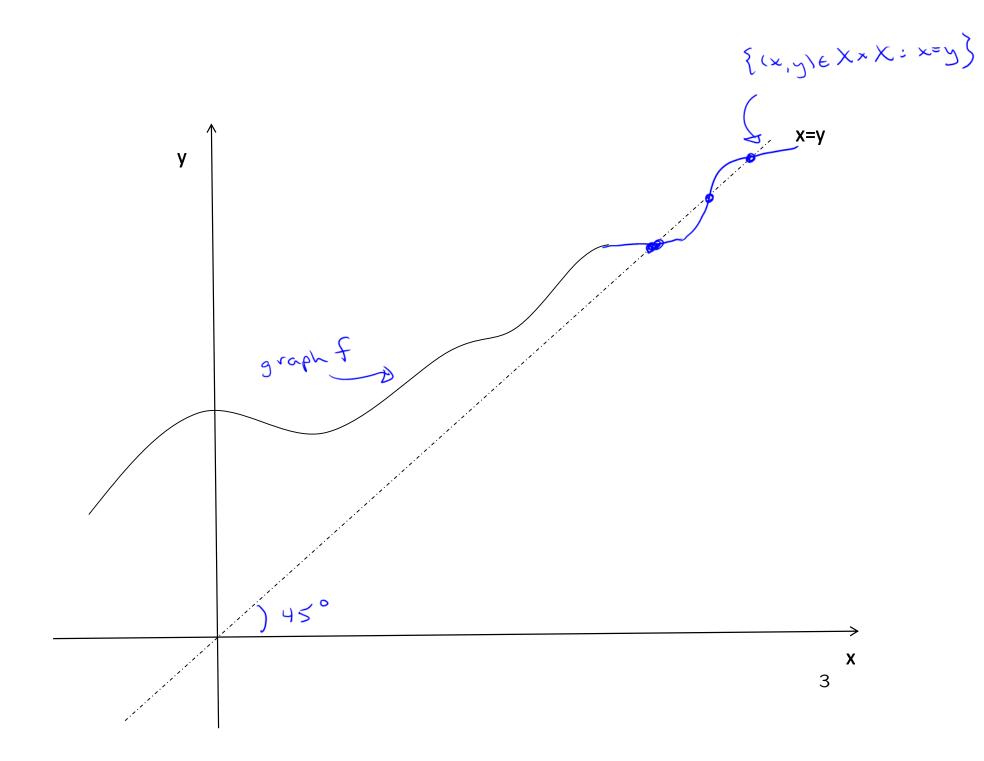
•  $Dx(a_0) = -[D_x f(x_0, a_0)]^{-1} D_a f(x_0, a_0)$ 

Recall:

### Fixed Points for Functions

**Definition 1.** Let X be a nonempty set and  $f: X \to X$ . A point  $x^* \in X$  is a fixed point of f if  $f(x^*) = x^*$ .

 $x^*$  is a fixed point of f if it is "fixed" by the map f.



### Fixed Points for Functions

#### **Examples:**

- 1. Let  $X = \mathbf{R}$  and  $f : \mathbf{R} \to \mathbf{R}$  be given by f(x) = 2x. Then x = 0 is a fixed point of f (and is the unique fixed point of f).
- 2. Let  $X = \mathbf{R}$  and  $f : \mathbf{R} \to \mathbf{R}$  be given by f(x) = x. Then every point in  $\mathbf{R}$  is a fixed point of f (in particular, fixed points need not be unique).
- 3. Let  $X = \mathbf{R}$  and  $f : \mathbf{R} \to \mathbf{R}$  be given by f(x) = x + 1. Then f has no fixed points.

4. Let X=[0,2] and  $f:X\to X$  be given by  $f(x)=\frac{1}{2}(x+1)$ . Then

$$f(x) = \frac{1}{2}(x+1) = x$$

$$\iff x+1 = 2x$$

$$\iff x = 1$$

So x=1 is the unique fixed point of f. Notice that f is a contraction (why?), so we already knew that f must have a unique fixed point on  $\mathbf R$  from the Contraction Mapping Theorem.

5. Let  $X = [0, \frac{1}{4}] \cup [\frac{3}{4}, 1]$  and  $f : X \to X$  be given by f(x) = 1 - x. Then f has no fixed points.

$$f(x) = -x = x \Rightarrow x = x$$

- 6. Let X=[-2,2] and  $f:X\to X$  be given by  $f(x)=\frac{1}{2}x^2$ . Then f has two fixed points, x=0 and x=2. If instead X'=(0,2), then  $f:X'\to X'$  but f has no fixed points on X'.
- 7. Let  $X = \{1, 2, 3\}$  and  $f: X \to X$  be given by f(1) = 2, f(2) = 3, f(3) = 1 (so f is a permutation of X). Then f has no fixed points.
- 8. Let X = [0,2] and  $f: X \to X$  be given by

$$f(x) = \begin{cases} x+1 & \text{if } x \le 1\\ x-1 & \text{if } x > 1 \end{cases}$$

Then f has no fixed points.

## A Simple Fixed Point Theorem

**Theorem 1.** Let X = [a, b] for  $a, b \in \mathbf{R}$  with a < b and let  $f : X \to X$  be continuous. Then f has a fixed point.

*Proof.* Let  $g:[a,b]\to \mathbf{R}$  be given by

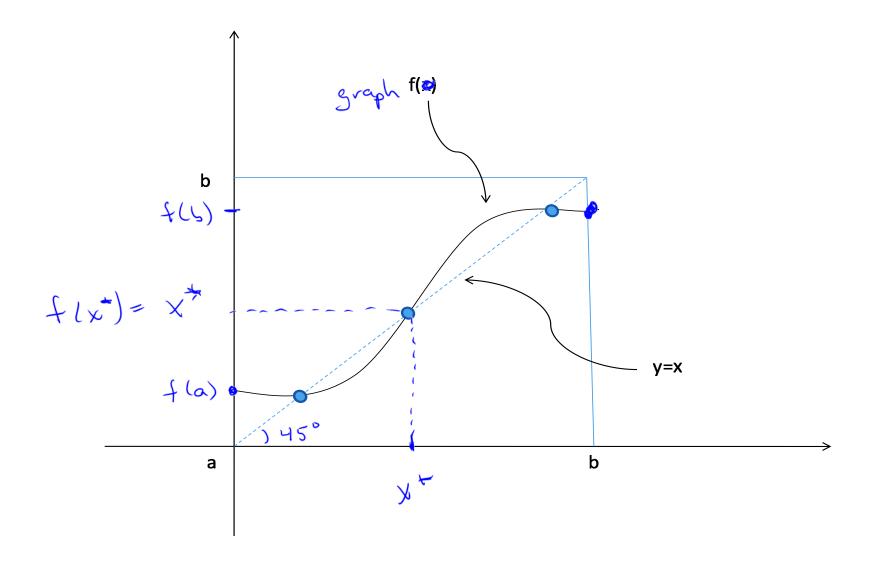
$$g(x) = f(x) - x$$
  $g(x) = 0 \iff x \in x \text{ a fixed}$ 

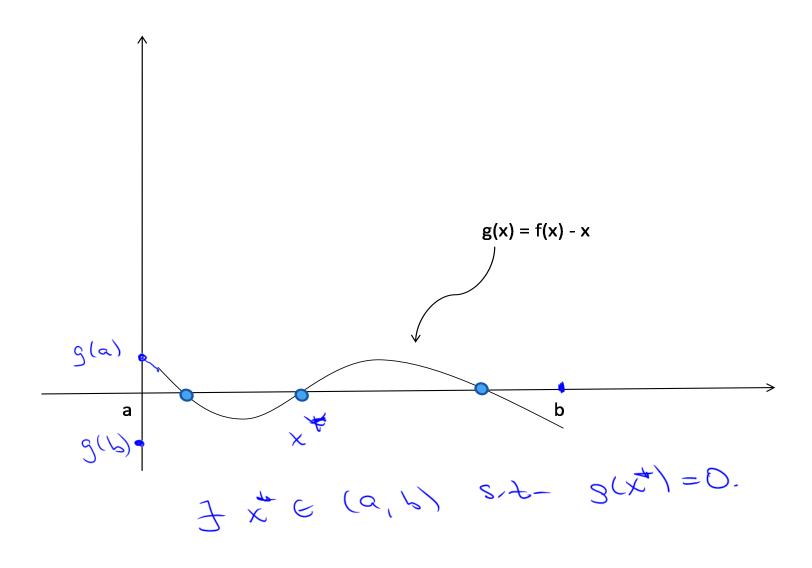
If either f(a)=a or f(b)=b, we're done. So assume f(a)>a and f(b)< b. Then

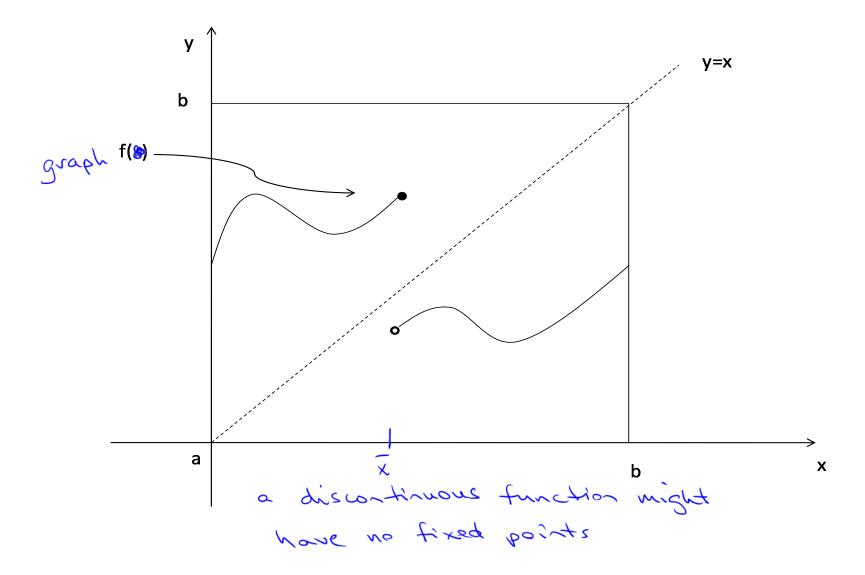
$$g(a) = f(a) - a > 0$$

$$g(b) = f(b) - b < 0$$

g is continuous, so by the Intermediate Value Theorem,  $\exists x^* \in (a,b)$  such that  $g(x^*)=0$ , that is, such that  $f(x^*)=x^*$ .







### Brouwer's Fixed Point Theorem

**Theorem 2** (Thm. 3.2. Brouwer's Fixed Point Theorem). Let  $X \subseteq \mathbb{R}^n$  be nonempty, compact, and convex, and let  $f: X \to X$  be continuous. Then f has a fixed point.

X & Re is convex if Ax, y & X Hackond (Jin)

Not convex

A convex

D not convex

9 uservex

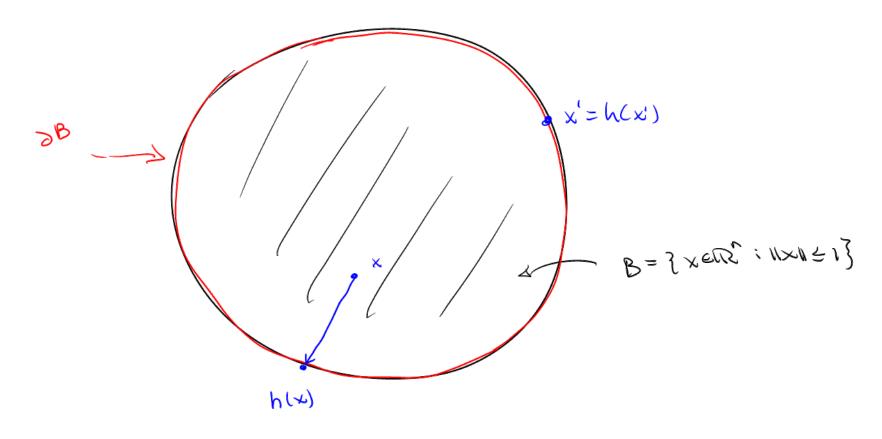
### Sketch of Proof of Brouwer

Consider the case when the set X is the unit ball in  ${\bf R}^n$ , i.e.  $X = B_1[0] = B = \{x \in \mathbf{R}^n : ||x|| \le 1\}.$  Let  $f : B \to B$  be a continuous function. Recall that  $\partial B$  denotes the boundary of B, so  $\partial B = \{ x \in \mathbf{R}^n : ||x|| = 1 \}.$ 

**Fact:** Let B be the unit ball in  $\mathbb{R}^n$ . Then there is no continuous function  $h: B \to \partial B$  such that h(x') = x' for every  $x' \in \partial B$ .

See J. Franklin, Methods of Mathematical Economics, for an elementary (but long) proof.

(also Y. Kamai, Am. math. Morthly, April 1981, pp. 264-368.)



Jh: B-> dB continuous such that  $\chi' = h(\chi')$   $\forall \chi' \in \partial B$ 

Now to establish Brouwer's theorem, suppose, by way of contradiction, that f has no fixed points in B. Thus for every  $x \in B$ ,  $x \neq f(x)$ .

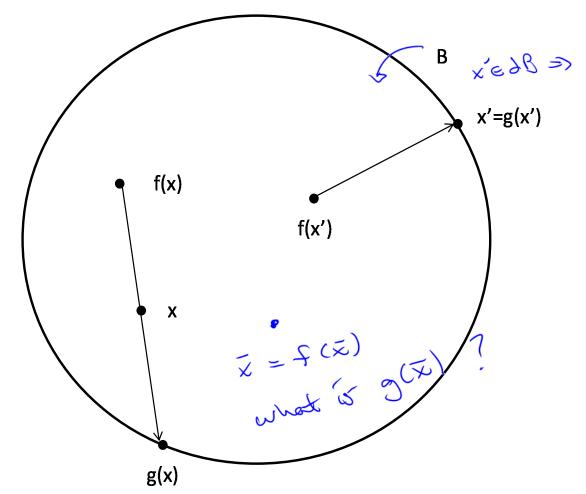
Since  $x \neq f(x)$  for every x, we can carry out the following construction. For each  $x \in B$ , construct the line segment originating at f(x) and going through x. Let g(x) denote the intersection of this line segment with  $\partial B$ .

This construction is well-defined, and gives a continuous function  $g: B \to \partial B$ . Furthermore, if  $x' \in \partial B$ , then x' = g(x'). That is,  $g|_{\partial B} = \mathrm{id}_{\partial B}$ . Since there are no such functions by the fact above, we have a contradiction. Therefore there exists  $x^* \in B$  such that  $f(x^*) = x^*$ , that is, f has a fixed point in B.

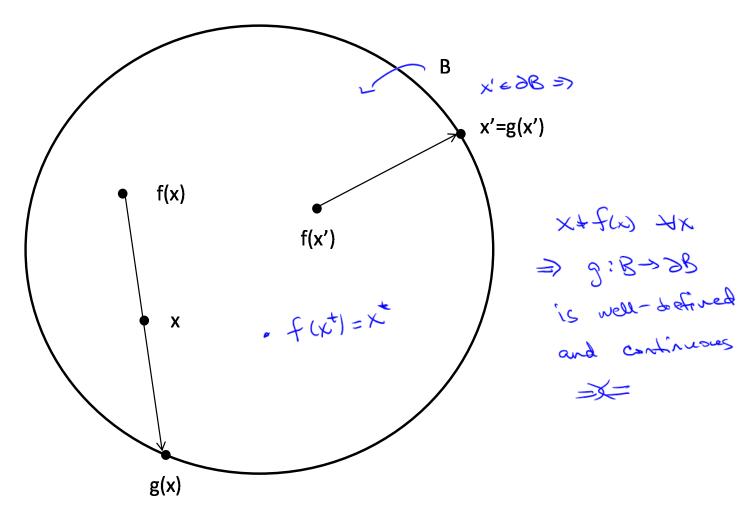
$$g(x) = x + tu$$
where  $u = \frac{x - f(x)}{\|x - f(x)\|}$ 

$$t = -x - u + \sqrt{1 - x \cdot x + (x - u)^2}$$

 $g: B \rightarrow \partial B$ continuous  $g(x') = x' + x' \in \partial B$ 



g(x) = x + tuwhere  $u = \frac{x - f(x)}{\|x - f(x)\|}$   $t = -x \cdot u + \sqrt{1 - x \cdot x + (x \cdot u)^2}$ 



## Fixed Points for Correspondences

**Definition 2.** Let X be nonempty and  $\Psi: X \to 2^X$  be a correspondence. A point  $x^* \in X$  is a fixed point of  $\Psi$  if  $x^* \in \Psi(x^*)$ .

Note here that we do *not* require  $\Psi(x^*) = \{x^*\}$ , that is  $\Psi$  need not be single-valued at  $x^*$ . So  $x^*$  can be a fixed point of  $\Psi$  but there may be other elements of  $\Psi(x^*)$  different from  $x^*$ .

#### **Examples:**

1. Let X = [0,4] and  $\Psi : X \to 2^X$  be given by

$$\Psi(x) = \begin{cases} [x+1, x+2] & \text{if } x < 2\\ [0, 4] & \text{if } x = 2\\ [x-2, x-1] & \text{if } x > 2 \end{cases}$$

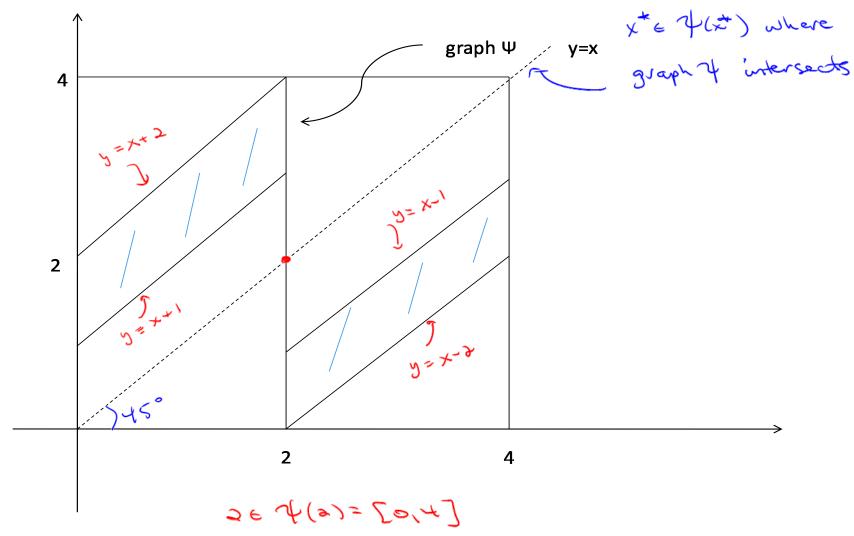
Then x = 2 is the unique fixed point of  $\Psi$ .

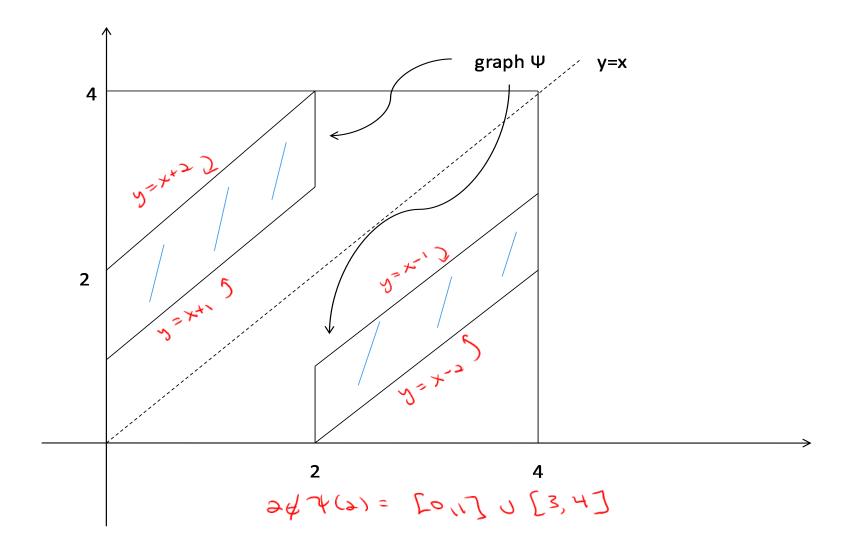
2. Let X = [0,4] and  $\Psi : X \to 2^X$  be given by

$$\Psi(x) = \begin{cases} [x+1, x+2] & \text{if } x < 2\\ [0,1] \cup [3,4] & \text{if } x = 2\\ [x-2, x-1] & \text{if } x > 2 \end{cases}$$

Then  $\Psi$  has no fixed points.







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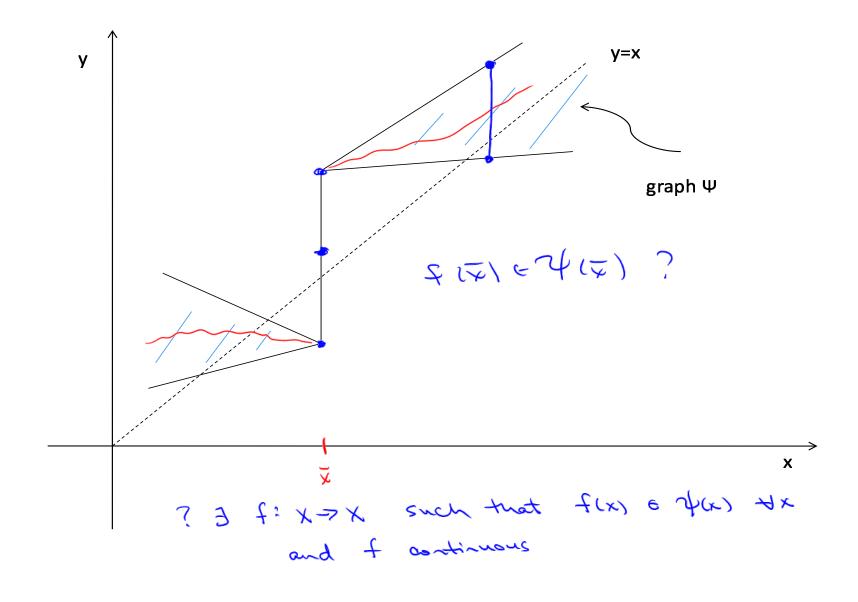
Note: Vie who in both cases

It: I(x) renempty, compact, convex

### Kakutani's Fixed Point Theorem

Theorem 3. (Thm. 3.4'. Kakutani's Fixed Point Theorem) Let  $X \subseteq \mathbb{R}^n$  be a non-empty, compact, convex set and  $\Psi: X \to 2^X$  be an upper hemi-continuous correspondence with non-empty, convex, compact values. Then  $\Psi$  has a fixed point in X.

*Proof.* (sketch) Here, the idea is to use Brouwer's theorem after appropriately approximating the correspondence with a function. The catch is that there won't necessarily exist a continuous selection from  $\Psi$ , that is, a continuous function  $f: X \to X$  such that  $f(x) \in \Psi(x)$  for every  $x \in X$ . If such a function existed, then by applying Brouwer to f we would have a fixed point of  $\Psi$  (because if  $\exists x^* \in X$  such that  $x^* = f(x^*)$ , then  $x^* = f(x^*) \in \Psi(x^*)$ ).



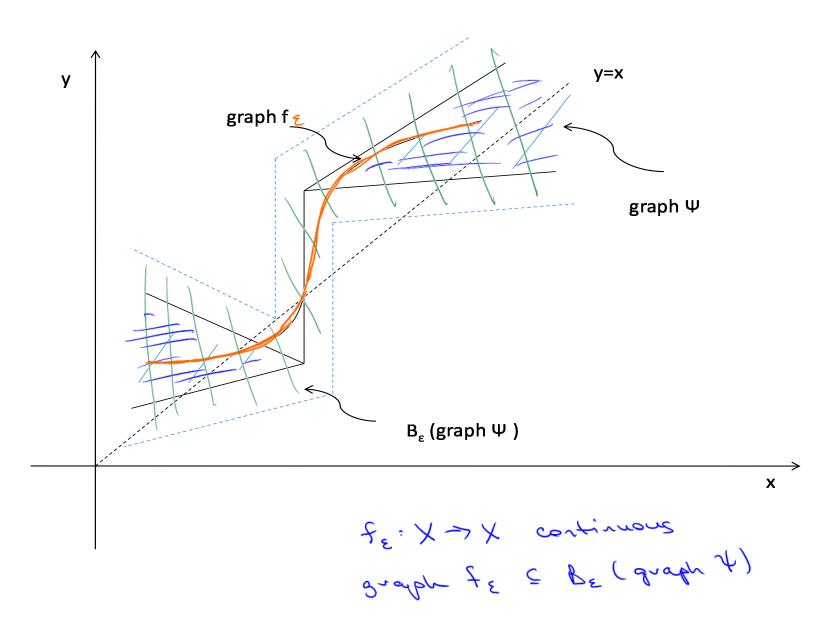
Y(x) convex 4xeX, 4 whe

Instead, we look for a weaker type of approximation. Let  $X \subset \mathbf{R}^n$  be a non-empty, compact, convex set, and let  $\Psi: X \to 2^X$  be an uhc correspondence with non-empty, compact, convex values. For every  $\varepsilon > 0$ , define the  $\varepsilon$  ball about graph  $\Psi$  to be

$$B_{\varepsilon}(\operatorname{graph} \Psi) =$$

$$\left\{ z \in X \times X : d(z, \operatorname{graph} \Psi) = \inf_{(x,y) \in \operatorname{graph} \Psi} d(z,(x,y)) < \varepsilon \right\}$$

Here d denotes the ordinary Euclidean distance. Since  $\Psi$  is uho and convex-valued, for every  $\varepsilon > 0$  there exists a continuous function  $f_{\varepsilon}: X \to X$  such that graph  $f_{\varepsilon} \subseteq B_{\varepsilon}$  (graph  $\Psi$ ).



Now by letting  $\varepsilon\to 0$ , this means that we can find a sequence of continuous functions  $\{f_n\}$  such that graph  $f_n \subseteq B_{\underline{1}}$  (graph  $\Psi$ ) for each n. By Brouwer's Fixed Point Theorem, each function  $f_n$  has a fixed point  $\hat{x}_n \in X$ , and

 $(\hat{x}_n, \hat{x}_n) = (\hat{x}_n, f_n(\hat{x}_n)) \in \text{ graph } f_n \subseteq B_{\frac{1}{n}}(\text{ graph } \Psi) \text{ for each } n$ 

So for each n there exists  $(x_n,y_n)\in \operatorname{graph}\Psi$  such that  $\operatorname{diam}(\hat{x}_n,\hat{x}_n)$ 

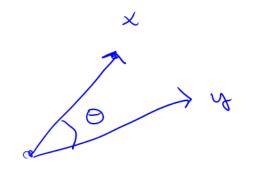
$$d(\widehat{x}_n, x_n) < \frac{1}{n}$$
 and  $d(\widehat{x}_n, y_n) < \frac{1}{n}$ 

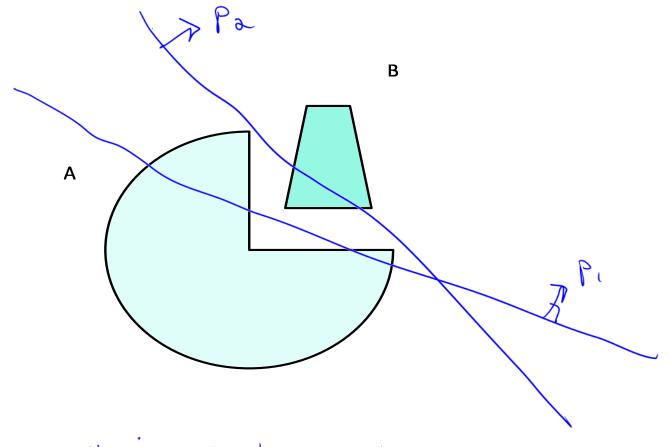
Since X is compact,  $\{\hat{x}_n\}$  has a convergent subsequence  $\{\hat{x}_{n_k}\}$ , with  $\widehat{x}_{n_k} \to \widehat{x} \in X$ . Then  $x_{n_k} \to \widehat{x}$  and  $y_{n_k} \to \widehat{x}$ . Since  $\Psi$  is uhc and closed-valued, it has closed graph, so  $(\hat{x}, \hat{x}) \in \text{graph } \Psi$ . Thus  $\hat{x} \in \Psi(\hat{x})$ , that is,  $\hat{x}$  is a fixed point of  $\Psi$ .

# Separating Hyperplane Theorems

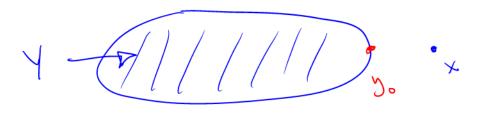
**Theorem 4** (1.26, Separating Hyperplane Theorem). Let  $A, B \subseteq \mathbb{R}^n$  be nonempty, disjoint convex sets. Then there exists a nonzero vector  $p \in \mathbb{R}^n$  such that

hyperplane: { ZER: V=Z=C} for some VER, V to, and some CER





Convexity important: re hyperplane separates
A and B



# Separating a Point from a Set

**Theorem 5.** Let  $Y \subseteq \mathbb{R}^n$  be a nonempty convex set and  $x \notin Y$ . Then there exists a nonzero vector  $p \in \mathbf{R}^n$  such that

$$p \cdot x \le p \cdot y \quad \forall y \in Y$$

*Proof.* We sketch the proof in the special case that Y is compact. We will see that in this case we actually get a stronger conclusion:

$$\exists p \in \mathbf{R}^n, p \neq 0 \text{ s.t. } p \cdot x$$

Choose  $y_0 \in Y$  such that  $||y_0 - x|| = \inf\{|y - x|| : y \in Y\}$ ; such a point exists because Y is compact, so the distance function g(y) = ||y - x|| assumes its minimum on Y. Since  $x \notin Y$ ,  $x \neq y_0$ , so  $y_0 - x \neq 0$ . Let  $p = y_0 - x$ . The set  $H = \{z \in \mathbf{R}^n : p \cdot z = p \cdot y_0\}$ 

$$H = \{ z \in \mathbf{R}^n : p \cdot z = p \cdot y_0 \}$$

is the hyperplane perpendicular to p through  $y_0$ . See Figure 12. Then

$$p \cdot y_0 = (y_0 - x) \cdot y_0$$

$$= (y_0 - x) \cdot (y_0 - x + x)$$

$$= (y_0 - x) \cdot (y_0 - x) + (y_0 - x) \cdot x$$

$$= ||y_0 - x||^2 + p \cdot x$$

$$> p \cdot x$$

We claim that

$$y \in Y \Rightarrow p \cdot y \ge p \cdot y_0 \rightarrow P \cdot x$$

If not, suppose there exists  $y \in Y$  such that  $p \cdot y . Given <math>\alpha \in (0,1)$ , let

$$w_{\alpha} = \alpha y + (1 - \alpha)y_0$$

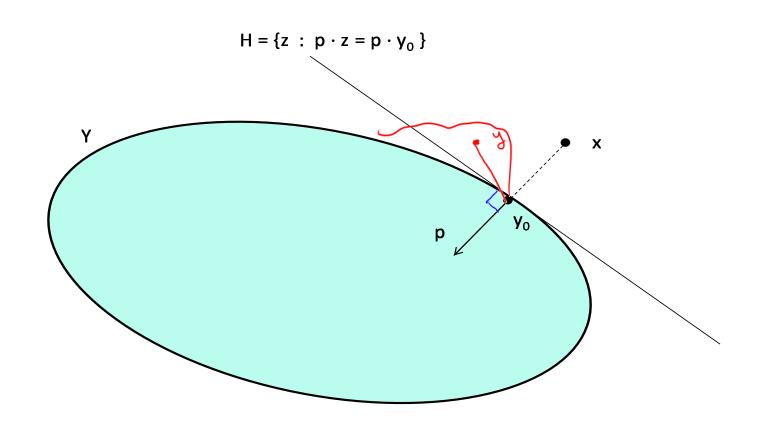
Since Y is convex,  $w_{\alpha} \in Y$ . Then for  $\alpha$  sufficiently close to zero,

$$\begin{aligned} ||x - w_{\alpha}||^{2} &= [|x - \alpha y - (1 - \alpha)y_{0}|]^{2} & \text{defn of wa} \\ &= |x - y_{0} + \alpha(y_{0} - y)|^{2} & \text{algebra} \\ &= |-p + \alpha(y_{0} - y)|^{2} & \text{defn of } \beta \\ &= |p|^{2} - 2\alpha p \cdot (y_{0} - y) + \alpha^{2}|y_{0} - y|^{2} & \text{more algebra} \\ &= |p|^{2} + \alpha \left(-2p \cdot (y_{0} - y) + \alpha|y_{0} - y|^{2}\right) & \text{wore algebra} \\ &= |p|^{2} & \text{for } \alpha \text{ close to 0, as } p \cdot y_{0} > p \cdot y & \text{as a so } \\ &= ||y_{0} - x||^{2} \end{aligned}$$

Thus for  $\alpha$  sufficiently close to zero,

$$||w_{\alpha} - x|| < ||y_{0} - x||$$

which implies  $y_0$  is not the closest point in Y to x, contradiction.



$$y = A - B$$
 convey vonempty

 $0 \neq y \Rightarrow y$ 
 $y = A - B$ 
 $y$ 

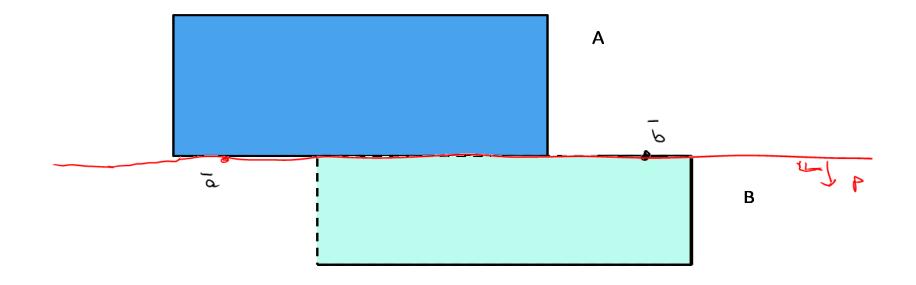
The general version of the Separating Hyperplane Theorem can be derived from this special case by noting that if  $A \cap B = \emptyset$ , then  $0 \not\in A - B = \{a - b : a \in A, b \in B\}$ .

## Strict Separation

For the special case of Y compact and  $X = \{x\}$ , we actually could *strictly separate* Y and X:

$$\times \not \downarrow \implies \exists p \in \mathbf{R}^n, p \neq 0 \text{ s.t. } p \cdot x$$

When can we do this in general? Will require additional assumptions...



A,B nonempty, disjoint, convex  $\Rightarrow$   $\exists p \in \mathbb{R}^n$ ,  $p \neq 0$  s.t.  $p : \alpha \leq p : b$   $\forall a \in A$   $\forall b \in B$ But  $p \cdot \overline{\alpha} = p \cdot \overline{b}$  for some  $\overline{a} \in A$  and  $\overline{b} \in B$ (for any such p)

## Strict Separation

Theorem 6. (Strict Separating Hyperplane Theorem) Let  $A, B \subseteq \mathbb{R}^n$  be nonempty, disjoint, closed, convex sets. Then there exists a nonzero vector  $p \in \mathbb{R}^n$  such that

$$p \cdot a$$