

Notes On Method-of-Moments Estimation

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Unconditional Moment Restrictions and Optimal GMM

Most estimation methods in econometrics can be recast as *method-of-moments* estimators, where the p -dimensional parameter of interest θ_0 is assumed to satisfy an *unconditional moment restriction*

$$E[m(w_i, \theta_0)] \equiv \mu(\theta) = 0 \quad (*)$$

for some q -dimensional vector of functions $m(w_i, \theta)$ of the observable data vector w_i and possible parameter value θ in some parameter space Θ . Assuming that θ_0 is the *unique* solution of this population moment equation (equivalent to identification when only (*) is imposed), a method-of-moments estimator $\hat{\theta}$ is defined as a solution (or near-solution) of a sample analogue to (*), replacing the population expectation by a sample average.

Generally, for θ_0 to uniquely solve (*), the number of components q of the moment function $m(\cdot)$ must be at least as large as the number of components p in θ – that is, $q \geq p$, known as the “order condition” for identification. When θ_0 is identified and $q = p$ – termed “just identification” – a natural analogue of the population moment equation for θ_0 defines the method-of-moment estimator as the solution to the p -dimensional sample moment equation

$$\begin{aligned} \bar{m}(\hat{\theta}) &\equiv \frac{1}{n} \sum_{i=1}^n m(w_i, \hat{\theta}) \\ &= 0, \end{aligned} \quad (**)$$

where w_1, \dots, w_n are all assumed to satisfy (*). The simplest setting, assumed hereafter, is that $\{w_i\}$ is a random sample (i.e., w_i is i.i.d), but this is hardly necessary; the $\{w_i\}$ can be dependent and/or have heterogeneous distributions, provided an “ergodicity” result $\bar{m}(\theta) - E[\bar{m}(\theta)] \xrightarrow{p} 0$ can be established.

Examples of estimators in this class include the maximum likelihood estimator (with $m(w_i, \theta)$ the “score function,” i.e., derivative of the log density of w_i with respect to θ for an i.i.d. sample) and the classical least squares estimator (with $w_i \equiv (y_i, x_i')'$ and $m(w_i, \theta) = (y_i - x_i'\theta)x_i$, the product of the residuals and regressors). Another example is the *instrumental variables* estimator for the linear model

$$y_i = x_i'\theta_0 + \varepsilon_i,$$

where y_i and $x_i \in q^p$ are subvectors of w_i and the error term ε_i is assumed to be orthogonal to some other subvector $z_i \in q^q$ of w_i , i.e.,

$$E[\varepsilon_i z_i] = E[(y_i - x_i' \theta_0) z_i] = 0.$$

When $q = p$ – i.e., the number of “instrumental variables” z_i equals the number of right-hand-side regressors x_i – then the *instrumental variables estimator*

$$\hat{\theta} = \left[\frac{1}{n} \sum_{i=1}^n z_i x_i' \right]^{-1} \frac{1}{n} \sum_{i=1}^n z_i y_i$$

is the solution to (**) when $m(w_i, \theta) = (y_i - x_i' \theta) z_i$.

Returning to the general moment condition (*), if $q > p$ – termed “overidentification” of θ_0 – the system of equations $\bar{m}(\theta) = 0$ is overdetermined, and in general no solution of this sample analogue to (*) will exist. In this case, an analogue estimator can be defined to make $\bar{m}(\theta)$ “close to zero,” by defining

$$\hat{\theta} = \arg \min_{\theta} S_n(\theta),$$

where $S_n(\theta)$ is a quadratic form in the sample moment function $\bar{m}(\theta)$,

$$S_n(\theta) \equiv [\bar{m}(\theta)]' A_n \bar{m}(\theta),$$

and A_n some non-negative definite, symmetric “weight matrix,” assumed to converge in probability to some limiting value A_0 , i.e.,

$$A_n \rightarrow^p A_0.$$

Here $\hat{\theta}$ is called a *generalized method of moments (GMM)* estimator, with large-sample properties that will depend upon the limiting weight matrix A_0 . Examples of possible (nonstochastic) weight matrices are $A_n = I_q$, an $q \times q$ identity matrix – which yields $S_n(\theta) = \|\bar{m}(\theta)\|^2$ – or

$$A_n = \begin{bmatrix} I_p & 0 \\ 0 & 0 \end{bmatrix},$$

for which the estimator $\hat{\theta}$ sets the first p components of $\bar{m}(\hat{\theta})$ equal to zero. More generally, A_n will have estimated components; once the asymptotic (normal) distribution of $\hat{\theta}$ is derived for a given value of A_0 , the optimal choice of A_0 (to minimize the asymptotic variance) can be determined, and a feasible efficient estimator can be constructed if this optimal weight matrix can be consistently estimated.

The consistency theory for $\hat{\theta}$ is standard for extremum estimators: the first step is to demonstrate uniform consistency of $S_n(\theta)$ to its probability limit

$$S(\theta) \equiv [\mu(\theta)]' A_0 \mu(\theta),$$

that is,

$$\sup_{\Theta} |S_n(\theta) - S(\theta)| \xrightarrow{p} 0,$$

and then to establish that the limiting minimand $S(\theta)$ is uniquely minimized at $\theta = \theta_0$, which follows if

$$A_0^{1/2} \mu(\theta) \neq 0 \quad \text{if} \quad \theta \neq \theta_0,$$

where $A_0^{1/2}$ is any square root of the weight matrix A_0 . Establishing both the uniform convergence of the minimand S_n to its limit S and uniqueness of θ_0 as the minimizer of S will require primitive assumptions on the distribution of w_i , the form of the moment function $m(\cdot)$, and the limiting weight matrix A_0 which vary with the particular problem.

Among the standard “regularity conditions” on the moment function $m(\cdot)$ is an assumption that it is “smooth” (i.e., continuously differentiable) in θ ; then, if θ_0 is assumed to be in the interior of the parameter space Θ , then with probability approaching one the consistent GMM estimator $\hat{\theta}$ will satisfy a first-order condition for minimization of S ,

$$\begin{aligned} 0 &= \frac{\partial S_n(\hat{\theta})}{\partial \theta} \\ &= 2 \left[\frac{\partial \bar{m}(\hat{\theta})}{\partial \theta'} \right]' A_n \bar{m}(\hat{\theta}). \end{aligned}$$

If the derivative of the average moment function $\bar{m}(\theta)$ converges uniformly in probability to its expectation in a neighborhood of θ_0 (which must be established in the usual way), then consistency of $\hat{\theta}$ implies that

$$\left[\frac{\partial \bar{m}(\hat{\theta})}{\partial \theta'} \right] \xrightarrow{p} M_0 \equiv \left[\frac{\partial \mu(\theta_0)}{\partial \theta'} \right].$$

This, plus convergence in probability of A_n to A_0 , means that the first-order condition can be rewritten as

$$0 = M_0' A_0 \bar{m}(\hat{\theta}) + o_p(\bar{m}(\hat{\theta})).$$

Inserting the usual Taylor’s series expansion of $\bar{m}(\hat{\theta})$ around the true value θ_0 ,

$$\bar{m}(\hat{\theta}) = \bar{m}(\theta_0) + \left[\frac{\partial \bar{m}(\hat{\theta})}{\partial \theta'} \right] (\hat{\theta} - \theta_0) + o_p(\|\hat{\theta} - \theta_0\|),$$

yields

$$\begin{aligned} 0 &= M'_0 A_0 \left[\bar{m}(\theta_0) + \left[\frac{\partial \bar{m}(\hat{\theta})}{\partial \theta'} \right] (\hat{\theta} - \theta_0) + o_p(\|\hat{\theta} - \theta_0\|) \right] + o_p(\bar{m}(\hat{\theta})) \\ &\equiv M'_0 A_0 \bar{m}(\theta_0) + M'_0 A_0 M_0 (\hat{\theta} - \theta_0) + q_n, \end{aligned}$$

where q_n is a generic remainder term. Assuming it can be verified that

$$q_n = o_p\left(\frac{1}{\sqrt{n}}\right)$$

by the usual methods, the normalized difference between the estimator $\hat{\theta}$ and the true value θ_0 has the asymptotically-linear representation

$$\sqrt{n}(\hat{\theta} - \theta_0) = [M'_0 A_0 M_0]^{-1} M'_0 A_0 \cdot \sqrt{n} \bar{m}(\theta_0) + o_p(1).$$

But $\sqrt{n} \bar{m}(\theta_0)$ is a normalized sample average of mean-zero, i.i.d. random vectors $m(w_i, \theta_0)$, so by the Lindeberg-Levy central limit theorem,

$$\sqrt{n} \bar{m}(\theta_0) \rightarrow^d \mathcal{N}(0, V_0),$$

where

$$\begin{aligned} V_0 &\equiv \text{Vaq}[m(w_i, \theta_0)] \\ &= E[m(w_i, \theta_0) m(w_i, \theta_0)'], \end{aligned}$$

and thus

$$\sqrt{n}(\hat{\theta} - \theta_0) \rightarrow^d \mathcal{N}(0, [M'_0 A_0 M_0]^{-1} M'_0 A_0 V_0 A_0 M_0 [M'_0 A_0 M_0]^{-1}),$$

which has a rather ungainly looking expression for the asymptotic covariance matrix.

By definition, an efficient choice of limiting weight matrix A_0 will minimize the asymptotic covariance matrix of $\hat{\theta}$ (in a positive semi-definite sense). The same proof as for the Gauss-Markov theorem can be used to show that this product of matrices will be minimized by choosing A_0 to make the “middle matrix” $M'_0 A_0 V_0 A_0 M_0$ equal to an “outside matrix” $M'_0 A_0 M_0$ being inverted. That is,

$$[M'_0 A_0 M_0]^{-1} M'_0 A_0 V_0 A_0 M_0 [M'_0 A_0 M_0]^{-1} \geq [M'_0 V_0^{-1} M_0]^{-1},$$

where the inequality means the difference in the two matrices is positive semi-definite; equality is obviously achieved if A_0 is chosen as

$$A_0^* \equiv V_0^{-1} = [\text{Vaq}[m(w_i, \theta_0)]]^{-1},$$

up to a (positive) constant of proportionality.

A feasible version of the optimal GMM estimator requires a consistent estimator of the covariance matrix V_0 . This can be obtained in two steps: first, by calculation of a non-optimal estimator $\hat{\theta}$ using an arbitrary sequence A_n for which $\hat{\theta}$ is consistent (e.g., $A_n = I_q$), and then by construction of a sample analogue to V_0 ,

$$\hat{V} \equiv \frac{1}{n} \sum_{i=1}^n m(w_i, \hat{\theta}) \left[m(w_i, \hat{\theta}) \right]'$$

The resulting *optimal GMM estimator* $\hat{\theta}^*$ will have asymptotic distribution

$$\sqrt{n}(\hat{\theta}^* - \theta_0) \rightarrow^d \mathcal{N}(0, [M_0' V_0^{-1} M_0]^{-1}),$$

and its asymptotic covariance matrix is consistently estimated by $[\hat{M}' \hat{V}^{-1} \hat{M}]^{-1}$, where

$$\hat{M} \equiv \frac{1}{n} \sum_{i=1}^n \frac{\partial m(w_i, \hat{\theta}^*)}{\partial \theta'}$$

Inference on θ_0 can then be based upon the usual large-sample normal theory.

For the example of the linear model with endogenous regressors,

$$\begin{aligned} y_i &= x_i' \theta_0 + \varepsilon_i, \\ 0 &= E[\varepsilon_i z_i] = E[(y_i - x_i' \theta_0) z_i], \end{aligned}$$

the relevant matrices for the asymptotic distribution of $\hat{\theta}^*$ are

$$\begin{aligned} M_0 &= E \left[\frac{\partial [(y_i - x_i' \theta_0) z_i]}{\partial \theta'} \right] \\ &= E [z_i x_i'] \end{aligned}$$

and

$$\begin{aligned} V_0 &= \text{Var}[(y_i - x_i' \theta_0) z_i] \\ &= E[(y_i - x_i' \theta_0)^2 z_i z_i']. \end{aligned}$$

The first step in efficient estimation of θ_0 might be based upon the (inefficient) *two-stage least squares*

(2SLS) estimator

$$\begin{aligned}\hat{\theta} &= \left(\left[\frac{1}{n} \sum_{i=1}^n x_i z_i' \right] \left[\frac{1}{n} \sum_{i=1}^n z_i z_i' \right]^{-1} \left[\frac{1}{n} \sum_{i=1}^n z_i x_i' \right] \right)^{-1} \\ &\quad \cdot \left[\frac{1}{n} \sum_{i=1}^n x_i z_i' \right] \left[\frac{1}{n} \sum_{i=1}^n z_i z_i' \right]^{-1} \left[\frac{1}{n} \sum_{i=1}^n z_i y_i \right], \\ &\equiv (\hat{M}' A_n \hat{M})^{-1} \hat{M}' A_n \left[\frac{1}{n} \sum_{i=1}^n z_i y_i \right]\end{aligned}$$

which is a GMM estimator using $m(w_i, \theta) \equiv (y_i - x_i' \theta) z_i$,

$$\hat{M} \equiv \left[\frac{1}{n} \sum_{i=1}^n z_i x_i' \right]$$

and

$$A_n \equiv \left[\frac{1}{n} \sum_{i=1}^n z_i z_i' \right]^{-1}.$$

With this preliminary, \sqrt{n} -consistent estimator of θ_0 , the efficient weight matrix is consistently estimated as

$$\hat{V}^{-1} \equiv \left[\frac{1}{n} \sum_{i=1}^n (y_i - x_i' \hat{\theta})^2 z_i z_i' \right]^{-1},$$

and the efficient GMM estimator is

$$\hat{\theta}^* \equiv (\hat{M}' \hat{V}^{-1} \hat{M})^{-1} \hat{M}' \hat{V}^{-1} \left[\frac{1}{n} \sum_{i=1}^n z_i y_i \right],$$

which has the approximate normal distribution

$$\hat{\theta}^* \overset{A}{\rightsquigarrow} \mathcal{N} \left(\theta_0, \frac{1}{n} (\hat{M}' \hat{V}^{-1} \hat{M})^{-1} \right).$$

If the error terms $\varepsilon_i \equiv y_i - x_i' \theta_0$ happen to be homoskedastic,

$$\begin{aligned}Vaq[\varepsilon_i | z_i] &\equiv \sigma^2(z_i) \\ &= \sigma_0^2,\end{aligned}$$

then

$$\begin{aligned}V_0 &\equiv E[\varepsilon_i^2 z_i z_i'] \\ &= \sigma_0^2 E[z_i z_i'] \\ &= \sigma_0^2 \text{plim } A_n,\end{aligned}$$

and the 2SLS estimator $\hat{\theta}$ would be asymptotically efficient, and asymptotically equivalent to the efficient GMM estimator $\hat{\theta}^*$.