

Problem Set 7  
Due in lecture, Tuesday, November 22, 2011

1. **Saddle-path of the q-theory model.** (Special ground rules for this problem: (1) You must try it first under exam conditions – no readings, no notes, no help. (2) You may then look at lecture notes and readings, but not consult with others or look at the midterm solutions. (3) You may then look at the midterm solutions and/or consult with others.)

Consider the 2 equations of the q-theory model,

$$\dot{q}(t) = rq(t) - \pi(K(t)), \quad \dot{K}(t) = f(q(t)).$$

a. Define the steady state of the model,  $(\bar{q}, \bar{K})$ . Show that the model's linear (Taylor) approximation in the neighborhood of the steady state takes the form:

$$[\dot{q}, \dot{K}]' \approx G[q - \bar{q}, K - \bar{K}]',$$

where  $G =$

A	B
C	0

Be sure to show how A, B, and C depend on exogenous parameters, the steady-state values of q and K, and/or the properties of  $\pi(\cdot)$  and  $f(\cdot)$ .

b. Show that the characteristic roots of the preceding 2x2 matrix are:

$$\lambda_1, \lambda_2 = \frac{r \mp \sqrt{r^2 - 4f'(1)\pi'(\bar{K})}}{2},$$

where  $\lambda_1 > 0$  and  $\lambda_2 < 0$ . Please indicate why the second condition holds.

c. Show that the eigenvectors of the matrix G are proportional to the matrix

$$X = \begin{array}{|c|c|} \hline \lambda_1/f'(1) & \lambda_2/f'(1) \\ \hline 1 & 1 \\ \hline \end{array}$$

d. Define  $[\tilde{q}, \tilde{K}]' \equiv X^{-1}[q - \bar{q}, K - \bar{K}]'$ , and note that this implies that  $[\dot{\tilde{q}}, \dot{\tilde{K}}]' = X^{-1}[\dot{q}, \dot{K}]'$ . Explain how that change of variables enables us to write the solution of our differential equation system in the form  $[\tilde{q}(t), \tilde{K}(t)]' = [\tilde{q}(0)e^{\lambda_1 t}, \tilde{K}(0)e^{\lambda_2 t}]'$  for arbitrary initial conditions  $\tilde{q}(0)$  and  $\tilde{K}(0)$ .

e. From this last relationship deduce that:

$$q(t) - \bar{q} = \tilde{q}(0)(\lambda_1/f'(1))e^{\lambda_1 t} + \tilde{K}(0)(\lambda_2/f'(1))e^{\lambda_2 t},$$

$$K(t) - \bar{K} = \tilde{q}(0)e^{\lambda_1 t} + \tilde{K}(0)e^{\lambda_2 t}. \quad (\text{OVER})$$

f. Recalling that  $\lambda_1 > 0$  and  $\lambda_2 < 0$ , identify the initial condition that will ensure the economy is on the convergent saddle-path in the usual phase diagram with  $K$  on the horizontal axis and  $q$  on the vertical axis.

g. For our linear approximation above, express the (linear) equation for the saddle-path in the form

$$q(t) - \bar{q} = \Omega[K(t) - \bar{K}]$$

for an appropriate constant slope  $\Omega < 0$ . Be sure to show how  $\Omega$  depends on the model parameters, the steady-state values of  $q$  and  $K$ , and/or the properties of  $\pi(\cdot)$  and  $f(\cdot)$ .

h. Recall that

$$\lambda_2 = \frac{r - \sqrt{r^2 - 4f'(1)\pi(\bar{K})}}{2}.$$

Discuss which parameters and steady state values affect the slope of the saddle-path. How do they impact the slope? Why?

2. (A variable investment subsidy in the  $q$  theory model.) Consider the  $q$  theory model of investment considered in lecture and in the book. Assume that initially  $K$  and  $q$  are at their long-run equilibrium values. Now suppose the government (unexpectedly and permanently) adopts a policy of subsidizing investment. Specifically, the government pays each firm  $\phi$  for each unit of investment it undertakes (and firms pay the government  $\phi$  for each unit of disinvestment they undertake). The subsidy paid at a point in time depends on the aggregate capital stock at that time:  $\phi = \phi(K(t))$ , with  $\phi(\$) > 0$ ,  $\phi'(\$) < 0$ .

- How, if at all, does the  $\dot{K} = 0$  locus change when the government adopts the subsidy?
- How, if at all, does the  $\dot{q} = 0$  locus change when the government adopts the subsidy?
- How, if at all, does the capital stock change at the moment the government adopts the subsidy?

3. Romer, Problem 9.7.

4. Consider an individual maximizing  $E_0[\sum_{t=0}^{\infty} \beta^t u(C_t)]$ , with our usual assumptions. If  $r^i$  denotes the return on some asset, asset  $i$ , from period 0 to period 1, then optimization requires:

- $\beta E_0[u'(C_1)] = E_0[(1 + r^i)]E_0[u'(C_0)] + \text{Cov}_0[r^i, u'(C_0)]$ .
- $E_0[u'(C_1)] = \beta E_0[(1 + r^i)]E_0[u'(C_0)] - \text{Cov}_0[r^i, u'(C_0)]$ .
- $E_0[1 + r^i] = E_0\left[\frac{\beta u'(C_1)}{u'(C_0)}\right]$ .
- $E_0\left[\frac{\beta u'(C_1)(1 + r^i)}{u'(C_0)}\right] = 1$ .

EXTRA PROBLEMS (NOT TO BE HANDED IN/ONLY SKETCHES OF ANSWERS WILL BE PROVIDED)

Romer, Problems 9.9, 9.12, 8.8, 8.9.